

APPLICATION
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TITLE: APPROXIMATE CALCULATOR FOR NON-LINEAR
FUNCTION AND MAP DECODER USING SAME

APPLICANT: KOJI KATO AND TAKAYUKI AONO

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**APPROXIMATE CALCULATOR FOR NON-LINEAR FUNCTION
AND MAP DECODER USING SAME**

CROSS REFERENCE TO RELATED APPLICATION

5 The present application is based on and incorporates herein
by reference Japanese Patent Application No. 2001-14582 filed on
January 23, 2001.

BACKGROUND OF THE INVENTION

10 1. Field of the Invention

 The present invention relates to an approximate calculator
for a non-linear function, an approximate calculator for a function
 $\log(1 + e^{-x})$, an approximate calculator for a function $\log(e^a +$
 $e^b)$ and a MAP decoder using the same.

15 2. Related Art

 A turbo decoder for decoding a turbo code is proposed. The turbo
code includes parallel concatenated convolutional codes with
interleaving. The turbo decoder receives and decodes the turbo code
while correcting errors. Referring to FIG. 7, the turbo decoder
20 includes two soft-output decoders 101, 102, two interleavers 103,
104, a deinterleaver 105, and a hard decision block 106. The
soft-output decoders 101, 102 perform decoding utilizing MAP
(Maximum A Posteriori) algorithm as follows.

 Referring to FIG. 8, a probability pdf that a bit is ``0'' and
25 a probability pdf that a bit ``1'' are calculated for all bits of

the received data $X(t)$ using a probability density function of the received data at step 201. Next, probabilities (state transition probabilities) γ are calculated for all branches of a trellis at step 202. At step 203, probabilities α (state probabilities) are calculated by forward iterations for all states and for all trellis levels (i.e., all bits of the received data). At step 204, the probabilities (state probabilities) β are calculated by backward iterations for all states and for all trellis levels.

Next, Information symbol likelihood λ is calculated for all trellis levels using the probabilities α, β . A priori likelihood (LDK) is calculated for all trellis levels based on information symbol likelihood λ at step 206, and it is converted to a priori probabilities corresponding to the respective states and fed back to step 202. At step 207, hard decision is made based on information symbol likelihood λ so that the received data is decoded.

This MAP decoding process may be implemented by a calculator shown in FIG. 9. That is, the probabilities pdf, the probabilities α, β, γ the information symbol likelihood λ , the a priori likelihood LDK and a priori probabilities prb can be computed by using the respective formulas shown in FIG. 9. However, it is impractical to implement the calculator by hardware or software, because the number of bits required for representing intermediate results is large.

Then it is proposed that one of various algorithms is employed so that the MAP decoding calculator is implemented by a smaller

circuit. For example, Log-BCJR algorithm (S. Bebedetto et. al, ``Soft-output decoding of parallel concatenated convolutional codes'', ICC 96) is known as an algorithm that enables alleviation of computational complexity so that the precision of decoding is maintained. According to Log-BCJR algorithm, the operations corresponding to the respective blocks shown in FIG. 9 are executed with respect to exponent parts, that is, the operations are executed in the log-domain.

Specifically, log pdf (i.e., $-(x-1)^2/2\sigma$) is calculated using received data x (σ represents variance). Log γ (i.e., $\log(\text{pdf.pdf.prb})$) is calculated utilizing a property of logarithms ($\log(\text{pdf.pdf.prb}) = \log \text{pdf} + \log \text{pdf} + \log \text{pdf}$). Log λ (i.e., $\log \frac{\sum(\alpha \cdot \beta \cdot \gamma)}{\sum(\alpha \cdot \beta \cdot \gamma)}$) is also calculated utilizing a property of logarithms

$$\left(\log \frac{\sum(\alpha \cdot \beta \cdot \gamma)}{\sum(\alpha \cdot \beta \cdot \gamma)} \right) = \log \sum(\alpha \cdot \beta \cdot \gamma) - \log \sum(\alpha \cdot \beta \cdot \gamma).$$

On the other hand, each of the probabilities α obtained by using a formula $\alpha_1 \cdot \gamma_1 + \alpha_2 \cdot \gamma_2$ where α_1, α_2 represent the previous states in the trellis and γ_1, γ_2 represent the branches of the respective previous states α_1, α_2 . Therefore, putting $\alpha_1 \cdot \gamma_1 = e^a$ and $\alpha_2 \cdot \gamma_2 = e^b$, $\log(e^a + e^b)$ should be calculated for obtaining the value of $\log \alpha$. Similarly, each of the probabilities β is obtained by using a formula $\beta_1 \cdot \gamma_3 + \beta_2 \cdot \gamma_4$ where β_1, β_2 represent the previous states in the trellis and γ_3, γ_4 represent the branches of the respective previous state β_1, β_2 . Therefore, putting $\beta_1 \cdot \gamma_3 = e^a$ and $\beta_2 \cdot \gamma_4 = e^b$,

$\log (e^a + e^b)$ should be calculated for obtaining the value of $\log \beta$.

When inequality $a > b$ is satisfied, $\log (e^a + e^b)$ equals $\log e^a(1 + e^{b-a})$ and therefore equals $a + \log (1 + e^{b-a})$. When inequality $b > a$ is satisfied, $\log (e^a + e^b)$ equals $\log e^b(1 + e^{a-b})$ and therefore equals $b + \log (1 + e^{a-b})$. Accordingly, $\log (e^a + e^b)$ is represented by the following formula:

$$\log (e^a + e^b) = \max (a, b) + \log (1 + e^{-|a-b|}) \quad \text{.....(1)}$$

It is proposed that the second term $\log (1 + e^{-|a-b|})$ of formula (1) is obtained by table lookup (NAGATA et al., "VLSI Implementation and Evaluation of W-CDMA Turbo Decoder", B-5-26, p. 411, 2000, Institute of Electronics, Information and Communication Engineers). In this case, formula (1) is calculated as follows.

Referring to FIG. 10, a subtracter 301 receives input data a , b , and outputs the difference $(a-b)$ between the input data a and b to a selector 302 and a table lookup block 303. The selector 302 further receives the input data a , b , and selects the larger one $\max (a, b)$ from the input data a and b based on the sign of the difference $(a-b)$. The selector 302 outputs the selected larger one $\max (a, b)$ to an adder 304. The table lookup block 303 retrieves a value of $\log (1 + e^{-|a-b|})$ from a lookup table based on the value of the difference $(a-b)$, and outputs it to the adder 304. The adder

304 generates the sum of the values of the larger one $\max(a, b)$ and $\log(1 + e^{-|a-b|})$, and outputs the generated sum as output y .

Thus $\log(e^a + e^b)$ can be calculated using the lookup table by a calculator shown in FIG. 10. However, in this case, the lookup table should include values of $\log(1 + e^{-|a-b|})$ corresponding to relatively many sampling points in order to maintain the precision of decoding. Further, putting $ldk = x$, $\log(1 + e^{-x})$ should be calculated for obtaining the value of $\log prb$. When an approximate value of $\log(1 + e^{-x})$ is calculated using a lookup table, the lookup table should include values of $\log(1 + e^{-x})$ corresponding to relatively many sampling points in order to maintain the precision of decoding. Therefore, the scale of a circuit which implements the calculator that generates an approximate value of $\log(1 + e^{-|a-b|})$ or $\log(1 + e^{-|a-b|})$ using a lookup table may be relatively large, and computation may be relatively complex.

This problem is not limited to the case of $\log(1 + e^{-|a-b|})$ or $\log(1 + e^{-x})$. When the value of an arbitrary non-linear function is obtained from a lookup table, the value of the non-linear function at a sampling point is used as the value of all the points belonging to the interval between the sampling point and the following sampling point as shown in FIG. 11. Therefore the lookup table should include values corresponding to relatively many sampling points in order to provide an approximate value sufficiently close to the actual value. However, a circuit that implements a calculator that includes a large lookup table may be relatively large-scale.

Then it is proposed that the non-linear function between two consecutive sampling points is linear-interpolated for compensating the insufficiency of the number of the sampling points. However, the calculator should perform division and multiplication for obtaining an approximate value in this case, because the slopes of straight lines that interpolate the non-linear function are unrestricted. Therefore, computation is complex, and the scale of a circuit that implements the calculator is relatively large in this case. Thus, in the case that the value of a non-linear function is digitally calculated using a lookup table that includes values at sampling points, the problems that computation is relatively complex and/or the scale of a calculator circuit is relatively large arise as a rule.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide a calculator which calculates an approximate value of a non-linear function using input data without performing complex calculation and can be implemented by a relatively small circuit.

It is another object of the present invention to provide a calculator which calculates an approximate value of a function $\log(1 + e^{-x})$ using input data x without performing complex calculation and can be implemented by a relatively small circuit.

It is a further object of the present invention to provide a calculator which calculates an approximate value of a function

log $(1 + e^{-|a-b|})$ using input data a, b without performing complex calculation and can be implemented by a relatively small circuit.

An approximate calculator according to the present invention includes decoder means, shifter means, and approximation output means. The decoder means outputs m-bit data (m is a natural number) that represents a value corresponding to the slope of a straight line based on the input data, and further outputs intercept data of the straight line based on the input data. The straight line interpolates a non-linear function for an interval that includes the value of the input data as one value of one of coordinates, and has a slope of 2^n (n is an integer). The intercept data represents the intercept of the straight line. The shifter means shifts the input data by |n| bits based on the m-bit data, and outputs the resultant data as first term data. The approximation output means generates and outputs an approximate value of the non-linear function based on the first term data and the intercept data.

The present calculator may be incorporated in a MAP decoder for recursively calculating forward state probabilities of a trellis and backward state probabilities of the trellis.

BRIEF DESCRIPTION OF THE DRAWINGS

The above and other objects, features and advantages of the present invention will become more apparent from the following detailed description made with reference to the accompanying drawings. In the drawings:

FIG. 1 is a block diagram showing an approximate calculator for a non-linear function according to the present invention;

FIG. 2 is graph representation showing how a non-linear function is linear-interpolated according to a first embodiment of the present invention;

FIG. 3 is graph representation showing how a non-linear function $Y = \log(1 + e^{-x})$ is linear-interpolated according to the first embodiment;

FIG. 4 is a block diagram showing an approximate calculator according to a second embodiment of the present invention;

FIG. 5 is graph representation showing how a non-linear function is linear-interpolated according to a modification of the first embodiment;

FIG. 6 is graph representation showing how the non-linear function $Y = \log(1 + e^{-x})$ is linear-interpolated according to the modification of the first embodiment;

FIG. 7 is a block diagram showing a turbo decoder according to related art;

FIG. 8 is a flowchart of a MAP decoding process executed by soft-output decoders of the turbo decoder according to related art;

FIG. 9 is a block diagram showing a calculator for executing the MAP decoding process of FIG. 8;

FIG. 10 is a block diagram showing a calculator for calculating the value of a non-linear function $\max(a, b) + \log(1 + e^{-|a-b|})$;

by using a lookup table that includes values of $\log (1 + e^{-|a-b|})$ at sampling points; and

FIG. 11 is graph representation showing how an approximate value of a non-linear function is obtained from values stored in a lookup table.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

(First Embodiment)

Referring to FIG. 1, a calculator according to a first embodiment of the present invention receives input data x , and generates an approximate value y of a non-linear function using the input data x . The calculator includes a decoder 11, a shifter 12 and an adder 13. The non-linear function is linear-interpolated interval by interval as shown in FIG. 2. Specifically, straight lines $Y = A \cdot X + B$ each of which has a slope of $\pm 2^n$ (n is an integer) are selected. The slopes of the selected straight lines are, for example, 4, 2, 1, 0.5, 0.25 and the like.

The Y-intercept B of each of the selected straight line is determined so that the error based on the differences between the approximate values y and the actual values y_a at sampling points is minimized. Therefore, if sufficiently many points are selected as the sampling points, an approximate value that is sufficiently close to the actual value can be obtained by using the selected straight lines. The entire non-linear function is interpolated by a polygonal line that includes segments of the respective straight

lines and further includes as vertices the intersections corresponding to the respective pairs of the adjacent straight lines.

Returning to FIG. 1, the decoder 11 receives the input data x , and retrieves, from a lookup table, m -bit data (m is a natural number) that represents a value corresponding to the slope $A = \pm 2^n$ of the straight line which interpolates an interval that includes the value of x as an X -value. Further the decoder 11 retrieves, from the lookup table, intercept data that represents the Y -intercept B of the straight line. The decoder 11 outputs the retrieved m -bit data to the shifter 12, and the retrieved intercept data to the adder 13. The shifter 12 further receives the input data x , and shifts it by $|n|$ bits rightward or leftward based on the sign and the value of the m -bit data. Thus data that represents the value of $2^n \cdot x$ is generated and outputted to the adder 13. The adder 13 generates the sum of the data $A \cdot x$ and the intercept data B , and outputs the generated sum as output y .

For example, a non-linear function $Y = \log(1 + e^{-x})$ is linear-interpolated as shown in FIG. 3 according to the present embodiment. That is, straight lines $Y = A \cdot X + B$ that have slopes of -0.5 , -0.25 , -0.125 , -0.0625 , -0.03125 and the like are selected, and the Y -intercept of each of the straight lines are determined so that the error based on the differences between the approximate values y and the actual values y_a at sampling points is minimized. The entire non-linear function is interpolated by a polygonal line

that includes segments of the respective straight lines and further includes as vertices the intersections corresponding to the respective pairs of the adjacent straight lines.

The calculator shown in FIG. 1 can calculate an approximate value of the function $Y = \log (1 + e^{-x})$ by the above linear interpolation. However, the slope of each of the straight lines that interpolate the function $Y = \log (1 + e^{-x})$ is represented as -2^n (n is an integer) in this case. Therefore a subtracter should be employed instead of the adder 13. The subtracter receives the result $2^n \cdot x$ of bit shift from the shifter 12, and subtracts it from the intercept data B. Thus an approximate value y of the function $Y = \log (1 + e^{-x})$ is obtained.

According to the present embodiment, the number of straight lines required for interpolating the entire non-linear function is relatively small, and the slopes of the straight lines are limited to $\pm 2^n$. Since the multiplication using a value of 2^n as a multiplier can be performed by bit shift, computation is not complex and the present calculator can be implemented by a relatively small circuit.

(Second Embodiment)

A calculator according to a second embodiment of the present invention receives input data a and b , and calculates an approximate value of a formula $\max(a, b) + \log (1 + e^{-|a-b|})$. This calculator is incorporated in a MAP decoder. The MAP decoder is incorporated in a turbo decoder shown in FIG. 7 as a soft-output decoder 101, 102 as described above, and implemented by software that includes

the process shown in FIG. 8 or hardware shown in FIG. 9. The calculator according to the present embodiment is used for calculating the probabilities α and β at steps 203 and 204 utilizing log-BCJR algorithm as described above, when the MAP decoder is implemented by software.

In order to obtain the probabilities α and β , putting $\alpha_1 \cdot \gamma_1 = e^a$ and $\alpha_2 \cdot \gamma_2 = e^b$ or $\beta_1 \cdot \gamma_3 = e^a$ and $\beta_2 \cdot \gamma_4 = e^b$, a value of $\log (e^a + e^b)$ should be calculated. $\log (e^a + e^b)$ is represented by a formula " $\max (a, b) + \log (1 + e^{-|a-b|})$ ", and the calculator according to the present embodiment calculates an approximate value of the formula as follows.

Referring to FIG. 4, digital input data a and b is inputted to a first subtracter 21. The first subtracter 21 outputs the difference (a-b) between the input data a and b to a selector 22 and to an absolute value circuit 27. The selector 22 further receives the input data a and b, and selects larger one $\max (a, b)$ of the input data a and b based on the sign of the difference (a-b). The selector 22 outputs the selected large one $\max (a, b)$ to an adder 26. The absolute value circuit 27 outputs the absolute value $|a-b|$ of the difference (a-b).

Putting $|a-b| = X$, $\log (1 + e^{-|a-b|})$ is represented as $\log (1 + e^{-X})$. Therefore a decoder 23, a shifter 24 and a second subtracter 25 can together generate a value of $\log (1 + e^{-|a-b|})$ similarly to the first embodiment. Specifically, the decoder 23 receives the absolute value $|a-b|$ of the difference (a-b), and retrieves, from

a lookup table, m-bit data (m is a natural number) which represents a value corresponding to the slope $A = -2^n$ of the straight line that interpolates an interval that includes the value of $|a-b|$ as an X-value. Further the decoder 23 retrieves, from the lookup table, intercept data that represents the Y-intercept B of the straight line. The decoder 23 outputs the m-bit data to the shifter 24, and the intercept data to the second subtracter 25.

The shifter 24 also receives the absolute value $|a-b|$ of the difference (a-b), and shifts it by $|n|$ bits based on the sign and value of the m-bit data. The shifter 24 outputs the resultant value as first term data of an approximate value of $\log(1 + e^{-|a-b|})$ to the second subtracter 25. The second subtracter 25 subtracts the value of the first term data from the Y-intercept B, and outputs the resultant value to the adder 26 as the approximate value of $\log(1 + e^{-|a-b|})$. The adder 26 generates the sum of the value of the larger one $\max(a, b)$ of the input data a, b and the approximate value of $\log(1 + e^{-|a-b|})$, and outputs the generated sum as an approximate value y of the formula $\max(a, b) + \log(1 + e^{-|a-b|})$.

(Modifications)

In the first embodiment, the non-linear function may be linear-interpolated as shown in FIG. 5. That is, points on which a tangent line has a slope of $\pm 2^n$ (n is an integer) are selected as sampling points. Specifically, the non-linear function is differentiated, and points on which the value of the derivative

of the non-linear function is $\pm 2^n$ (4, 2, 1, 0.5, 0.25 or the like) are selected as the sampling points.

The entire non-linear function is interpolated by a polygonal line that includes segments of the respective tangent lines and further includes as vertices the intersections corresponding to the respective pairs of the adjacent tangent lines. According to the present modification, the non-linear function $Y = \log(1 + e^{-x})$ is interpolated by tangent lines whose slopes are -0.5, -0.25, -0.125, -0.0625, -0.03125 and the like as shown in FIG. 6.

The calculator according to the above embodiments may be used for other cases in which a value of a non-linear function should be calculated. For example, the calculator may be used for calculating the information symbol likelihood λ at step 205 of FIG. 8, if necessary.